

Stone duality proofs for distributed computability theorems

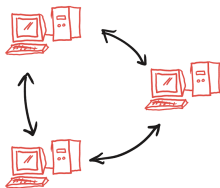
TACL '26

Cameron Calk
Emmanuel Godard

Aix-Marseille Université
Laboratoire d'Informatique et des Systèmes (LIS)

Overview

In distributed computing, several processes **communicate** in order to solve a **task** (consensus, renaming, ...).

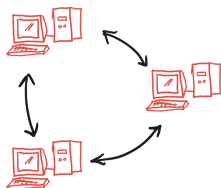


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*Which tasks can be **solved** in a given **model** of communication?*

Lack of global information is the main obstruction to task-solvability.



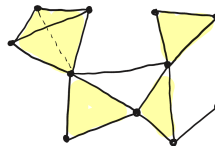
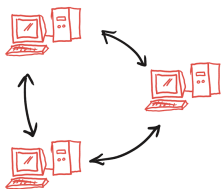
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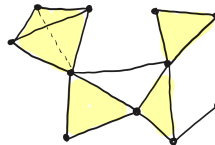
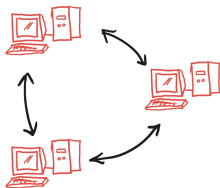
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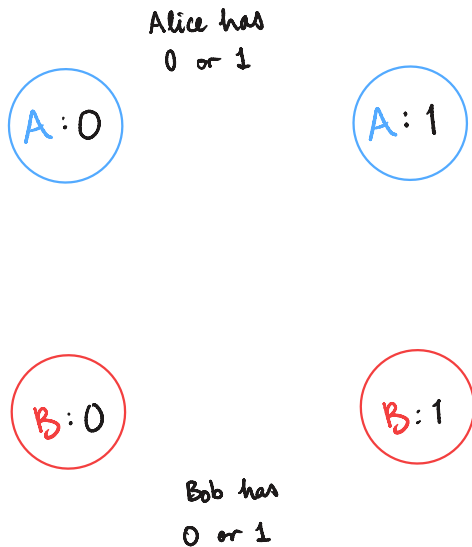
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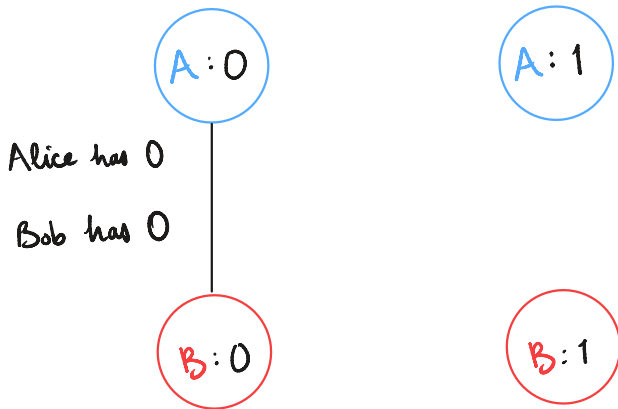
We extend this line of work using **spectral spaces**.



A toy example



A toy example

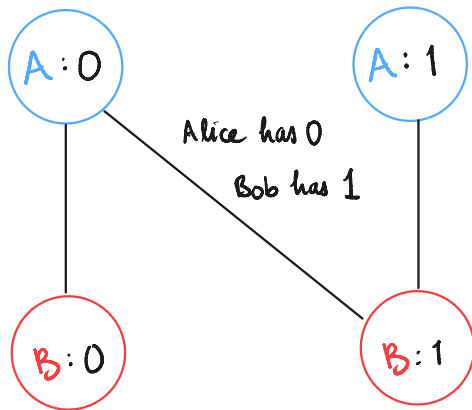


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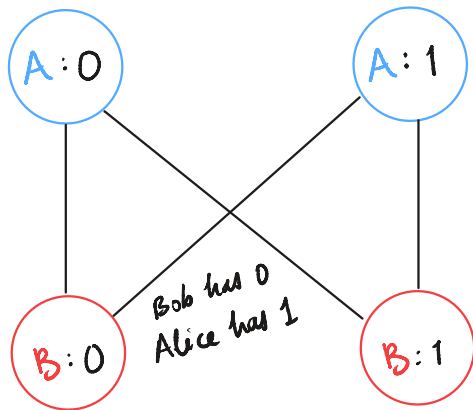


Alice has 1
Bob has 1

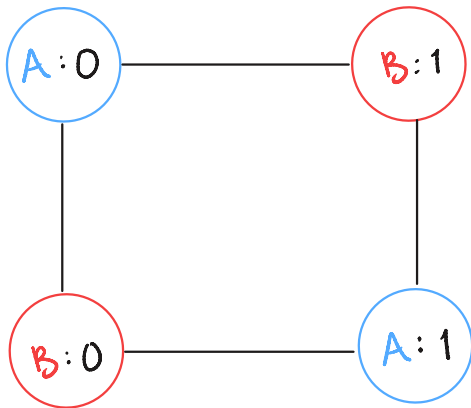
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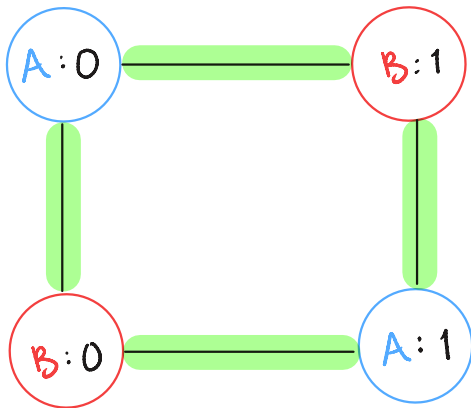


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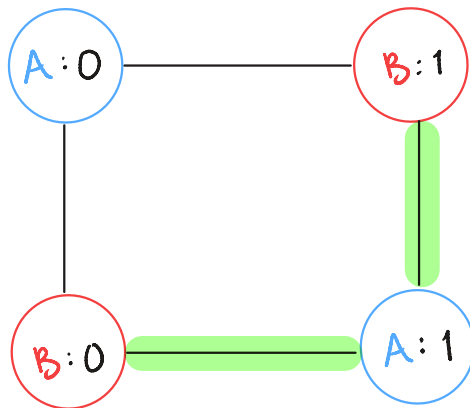
A toy example

Encodes all possible global states



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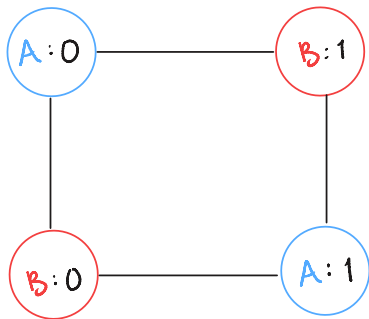
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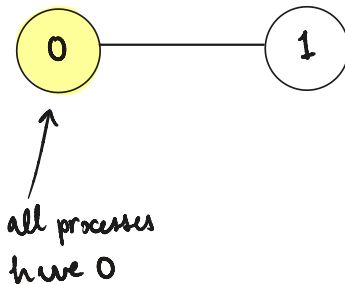
In this local state, Alice doesn't know which value Bob has

A toy example

With names and values
(coloured)

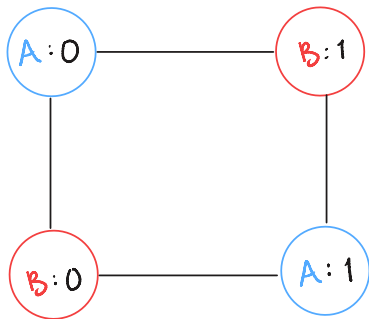


With only values
(colourless)

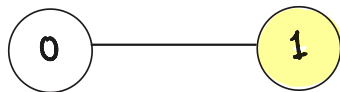


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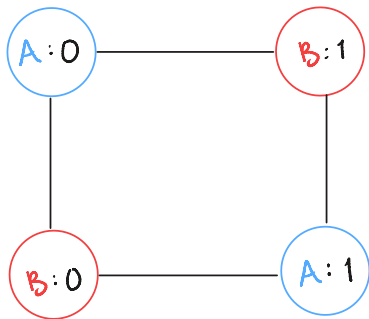
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↑
all processes
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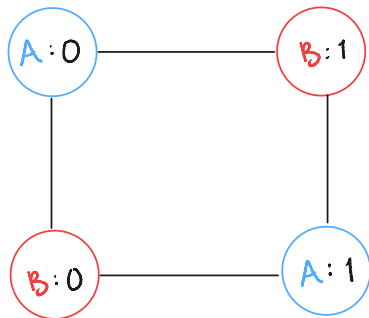
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There is at least one
process with 0, and
at least one with 1.

A toy example

Now, Alice and Bob communicate ...



There are three possibilities

- $A \rightarrow B$

Bob sees Alice's value, but she doesn't see his.

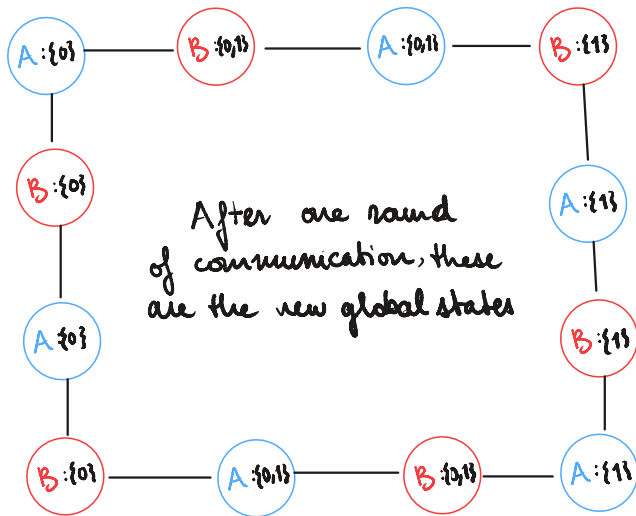
- $A \leftrightarrow B$

Alice and Bob see each other's values.

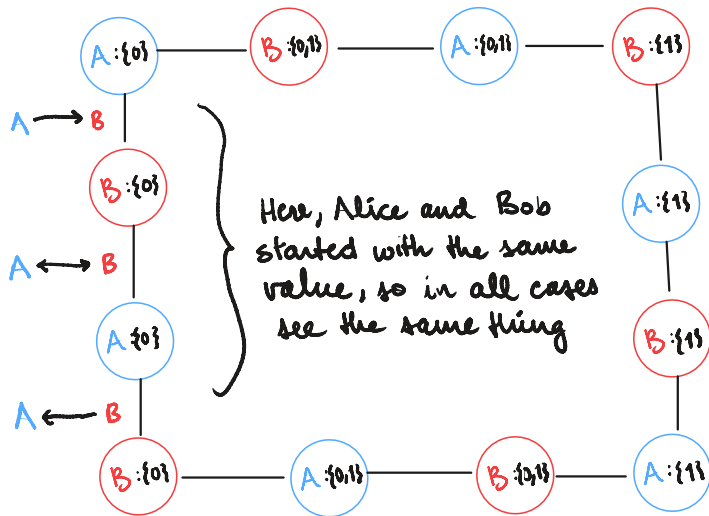
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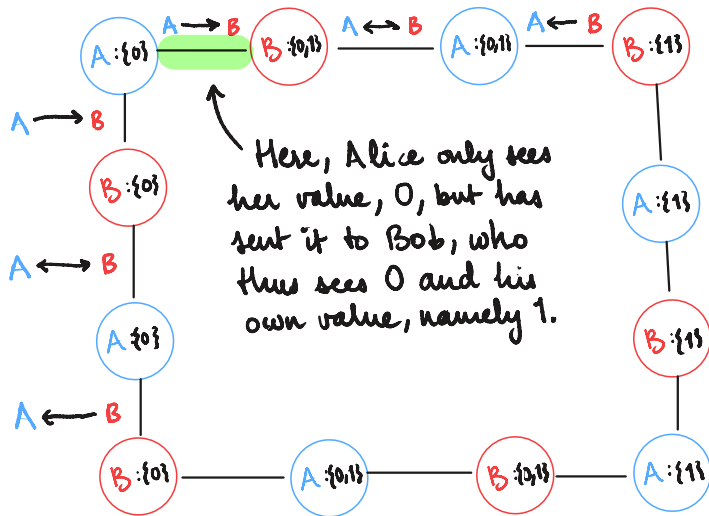
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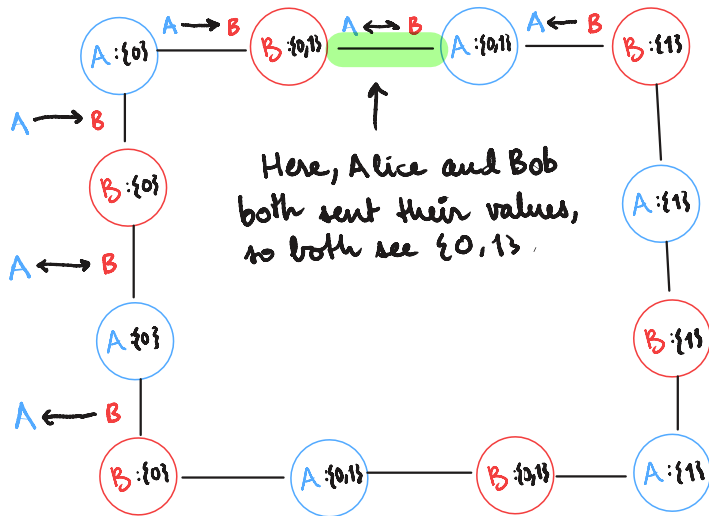
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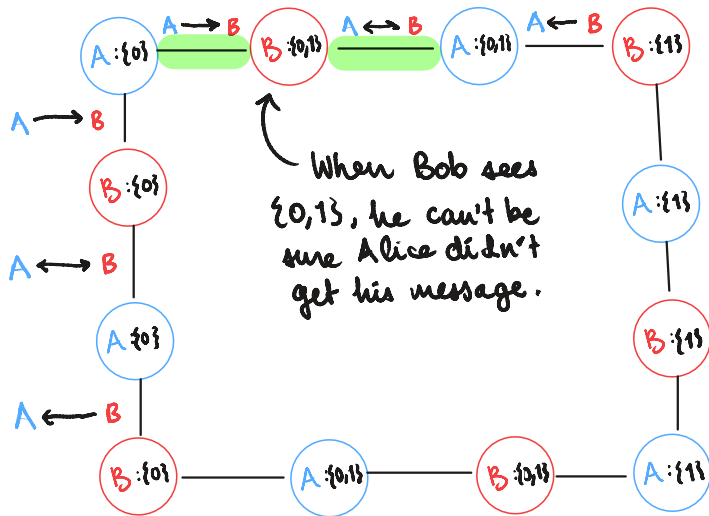
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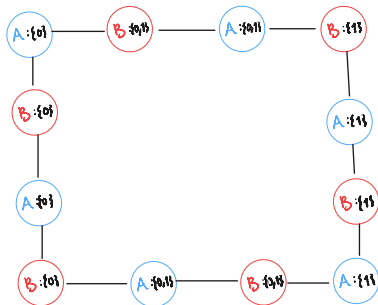
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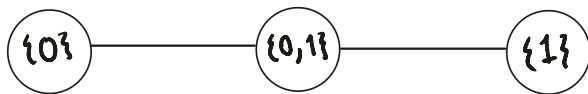
A toy example



A toy example



Forgetting about
names, we obtain
this



A toy example

So, communication transforms the initial configuration:

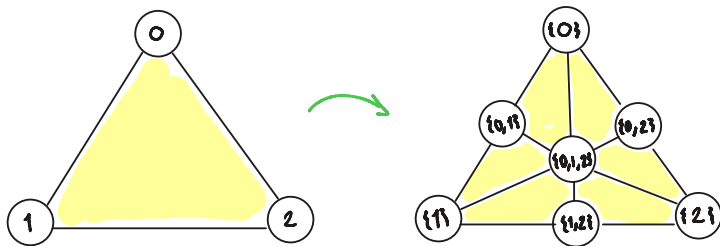


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This generalises to any number of values:

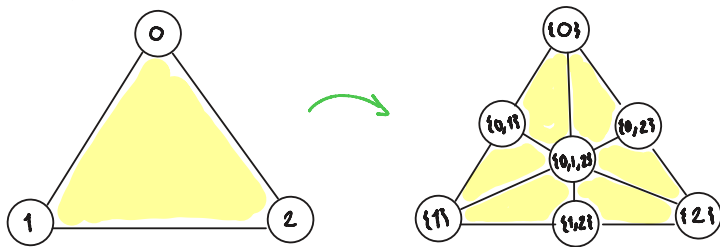


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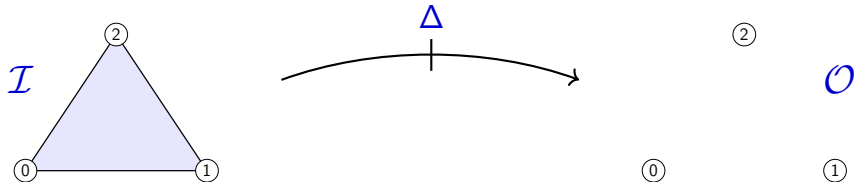
This generalises to any number of values:



We have encoded distributed knowledge in simplicial complexes, and a communication protocol as a transformation thereof.

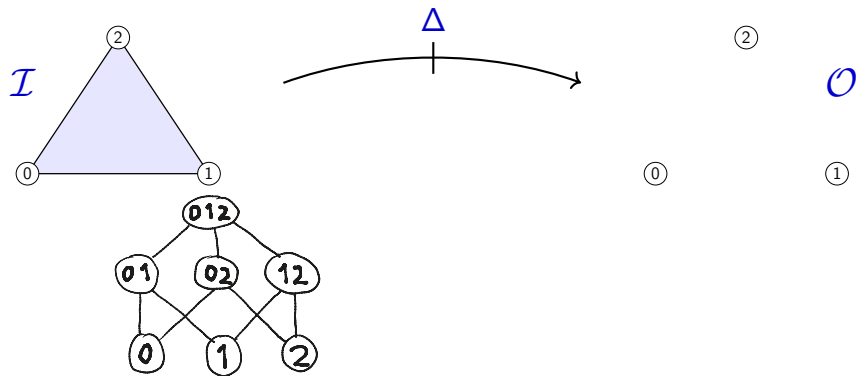
Simplicial semantics

Simplicial semantics of task-solvability



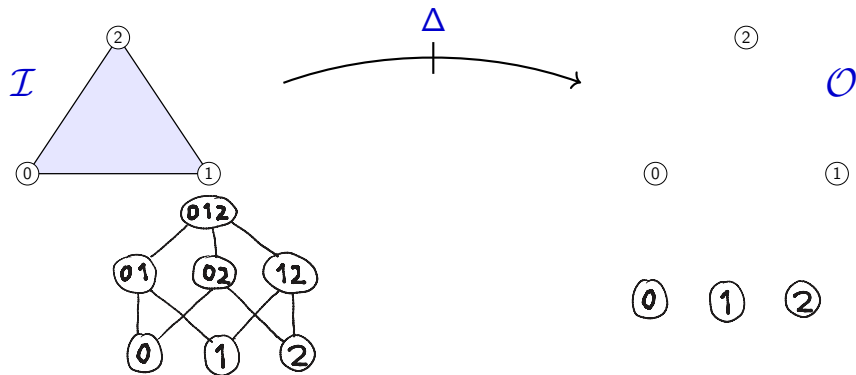
A distributed **task** (specification) is a relation between an input complex and an output complex.

Simplicial semantics of task-solvability



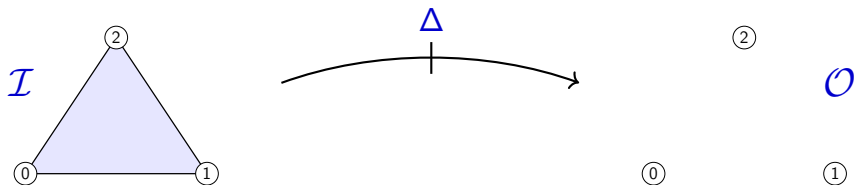
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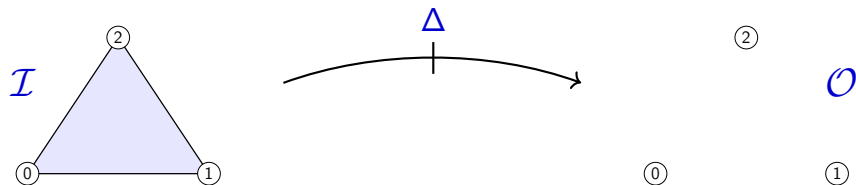
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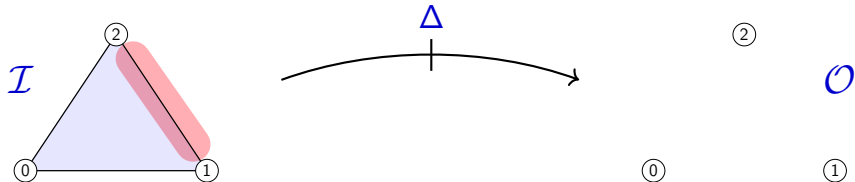
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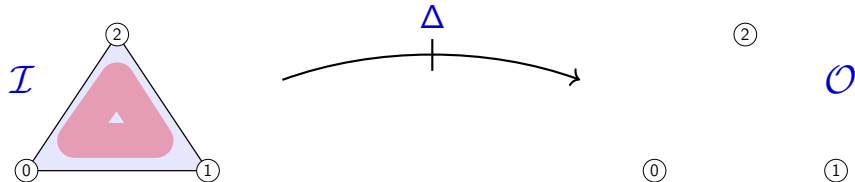
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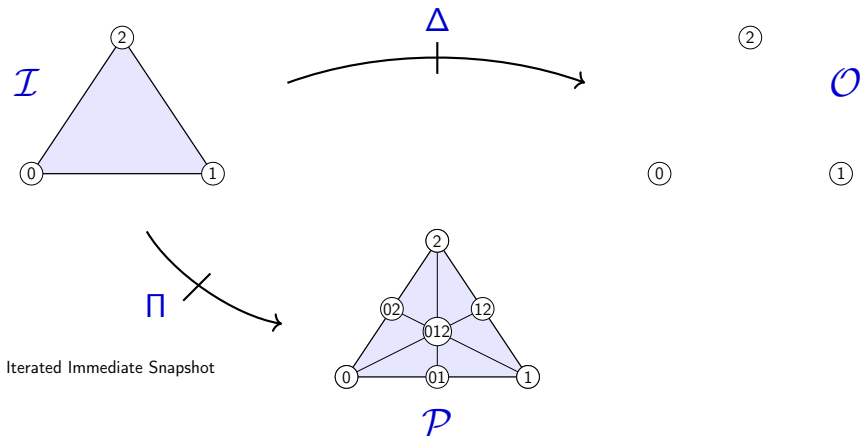
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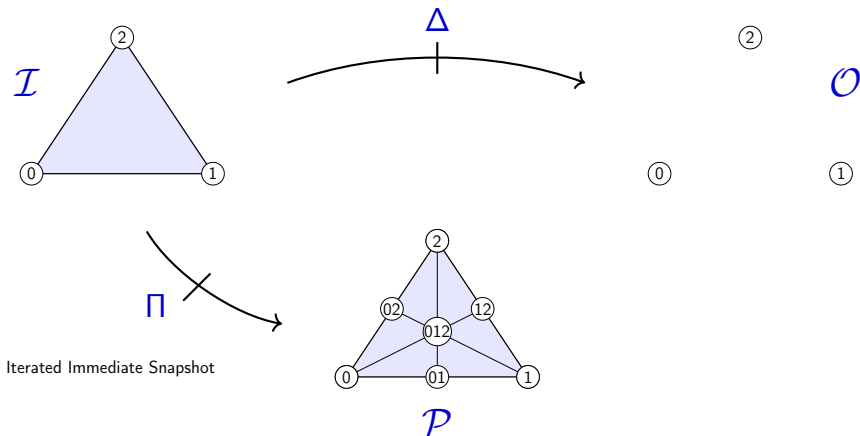
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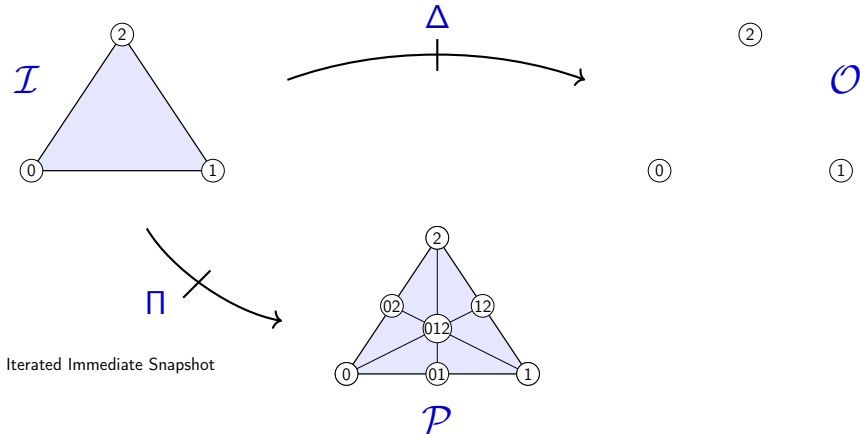
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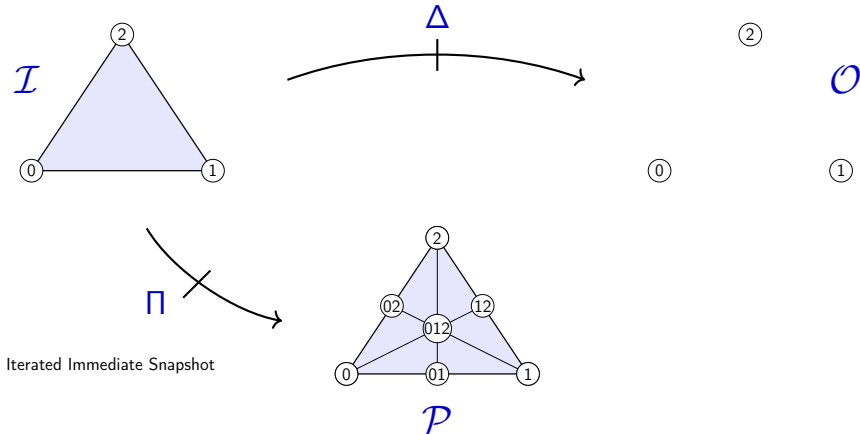
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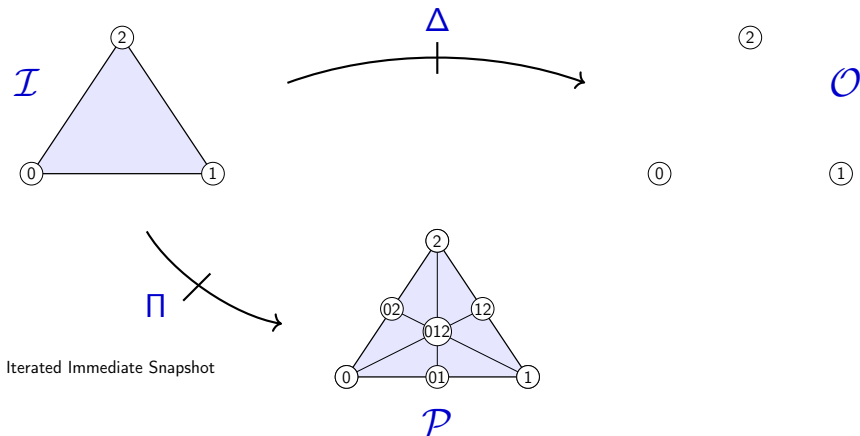
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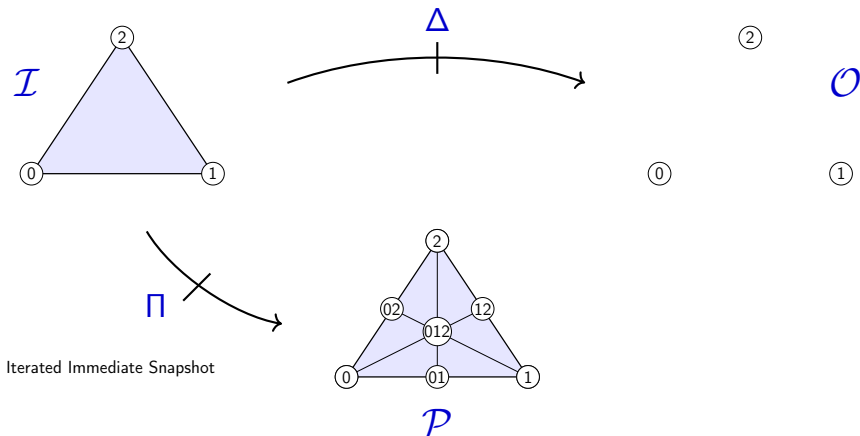
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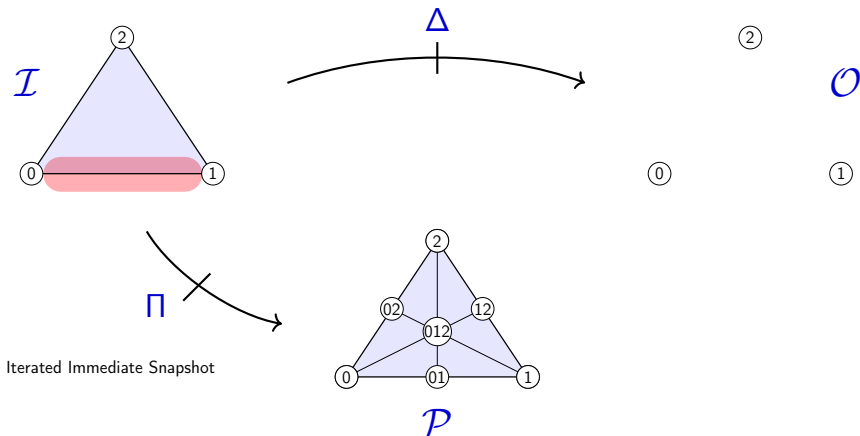
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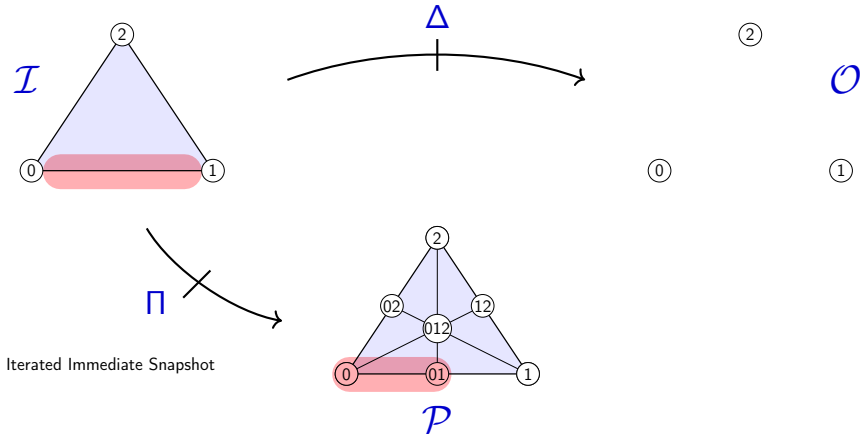
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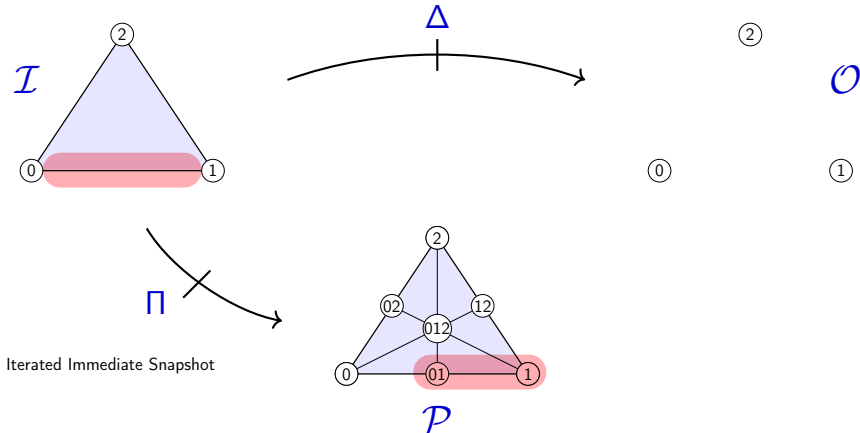
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Iterated Immediate Snapshot

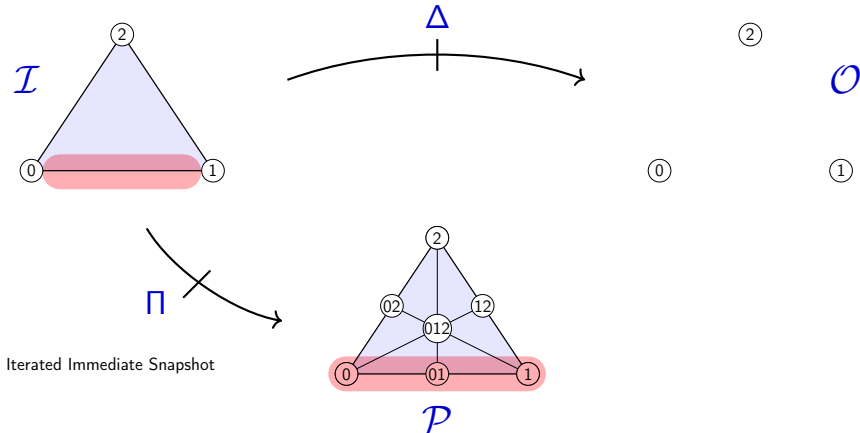
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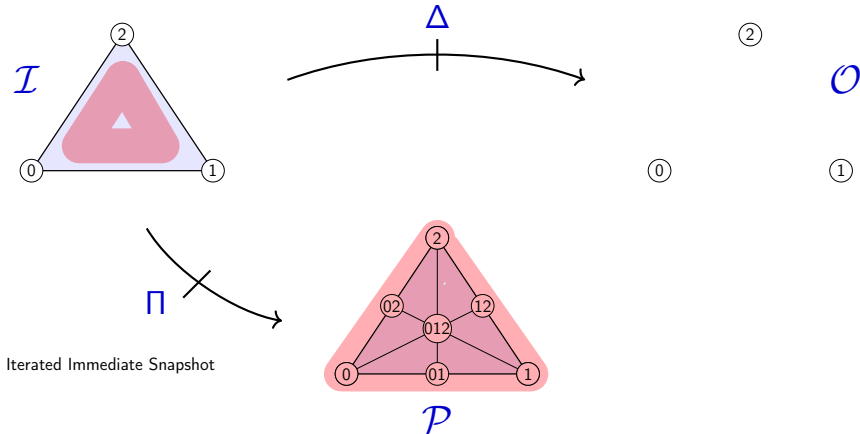
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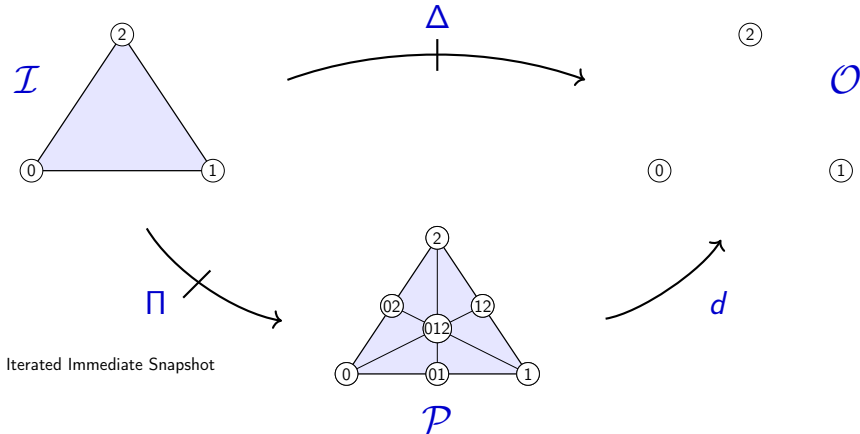
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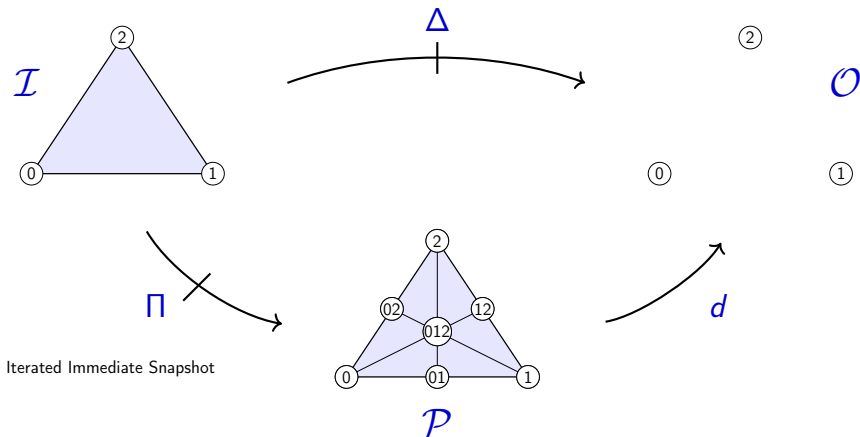
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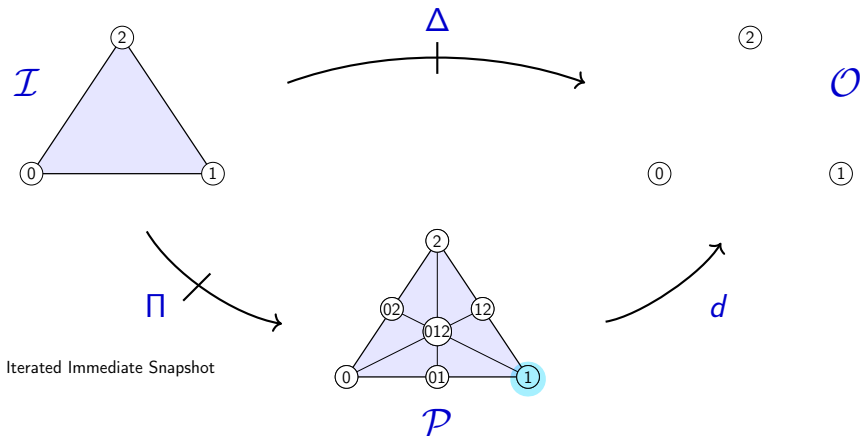
A **decision algorithm** is a simplicial map sending local states to valid outputs.

Simplicial semantics of task-solvability



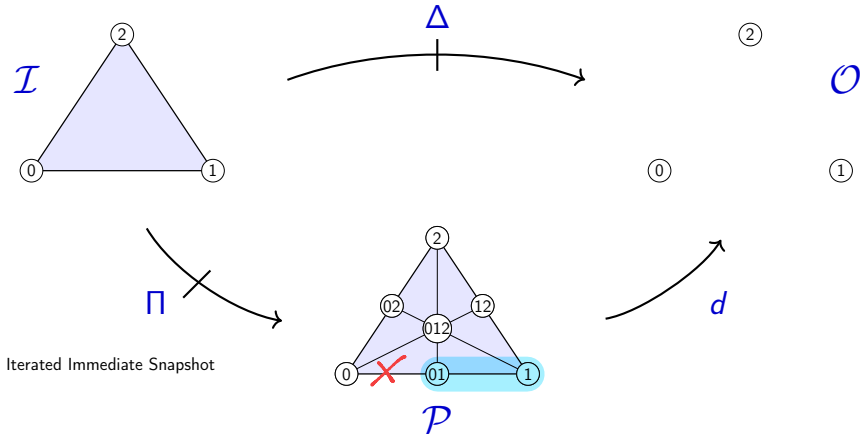
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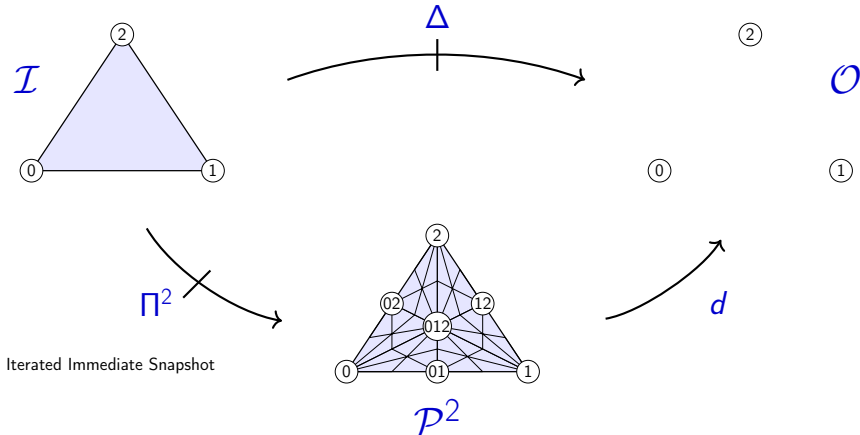
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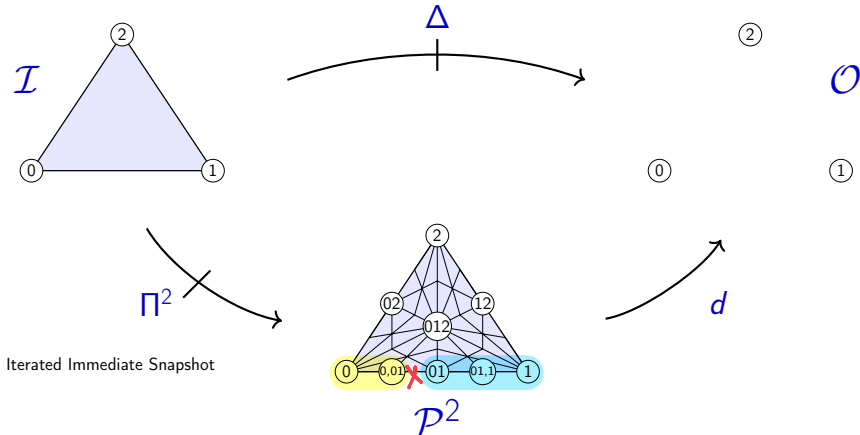
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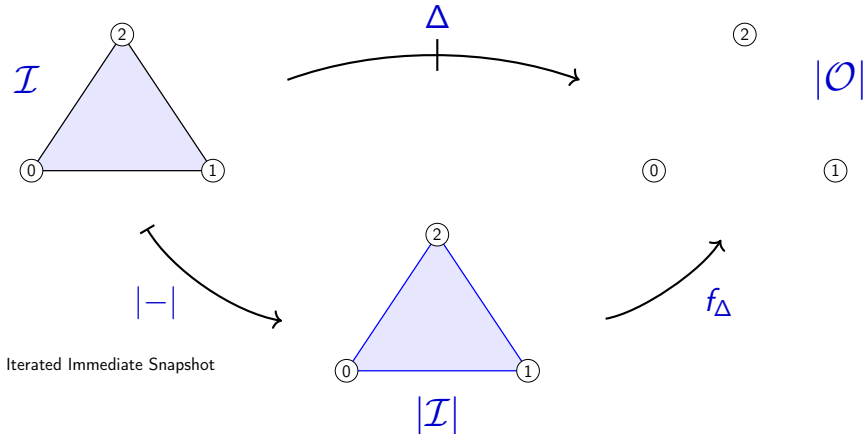
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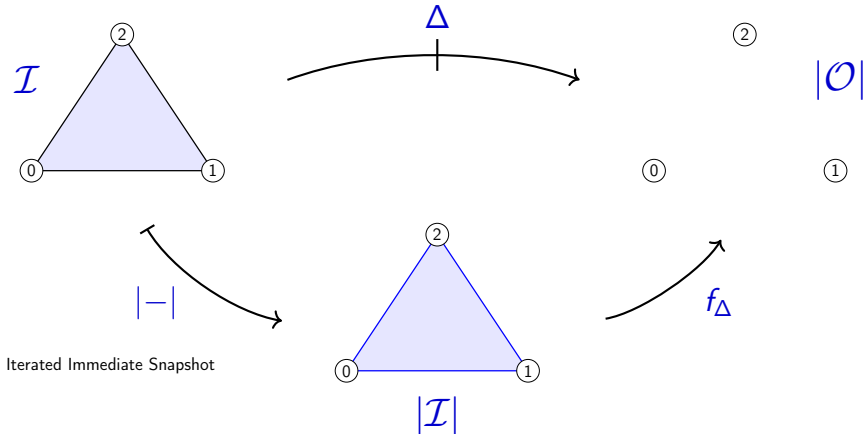


Theorem ([Herlihy, Shavit])

A colorless task $(\mathcal{I}, \mathcal{O}, \Delta)$ is solved by the IIS protocol $\iff$

There exists a continuous map $f_\Delta : |\mathcal{I}| \rightarrow |\mathcal{O}|$.

Simplicial semantics of task-solvability



Theorem ([Herlihy, Shavit], [Saks, Zarahoglu], Gödel prize '04)

A colorless task $(\mathcal{I}, \mathcal{O}, \Delta)$ is solved by a wait-free protocol

$\iff$

There exists a continuous map $f_\Delta : |\mathcal{I}| \rightarrow |\mathcal{O}|$.

Duality intervenes

Duality

The relations Δ and $\sqsupseteq$ can be seen as maps from **finite posets** to **down-sets of finite posets**.

$$\Gamma \subseteq \mathcal{C} \times \mathcal{C}' \quad \Leftrightarrow \quad \gamma : \mathcal{C} \longrightarrow \mathcal{D}(\mathcal{C}')$$

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Birkhoff duality expresses a **contravariant equivalence** between their respective categories:

$$\begin{array}{ccccc} P & & & & \mathcal{D}(P) \\ f \downarrow & \xrightarrow{\mathcal{D}(-)} & \text{Pos}_f & \xrightarrow{\quad} & \uparrow f^{-1} \\ Q & & \text{DL}_f & \xleftarrow{\mathcal{J}(-)} & \mathcal{D}(Q) \end{array}$$

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Stone duality generalises this to the infinite case:

$$\begin{array}{ccccc}
 \text{Spectral spaces} & \text{Spec} & \begin{array}{c} \xrightarrow{\mathcal{KO}(-)} \\ \xleftarrow{\text{St}(-)} \end{array} & \text{DL} & \text{Distributive lattices}
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A homomorphism appears!

In the topological approach to distributed computing, carrier maps associated to protocols must satisfy **extra conditions**.

Indeed, a **protocol map** $\pi : \mathcal{I} \rightarrow \mathcal{D}(\mathcal{P})$ is such that

$$\pi(\sigma \cap \tau) = \pi(\sigma) \cap \pi(\tau).$$

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$\pi^\vee : \mathcal{D}(\mathcal{I}) \rightarrow \mathcal{D}(\mathcal{P})$ sends a subcomplex $J \subseteq \mathcal{I}$ to $\bigcup_{\sigma \in J} \pi(\sigma)$.

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Dualising, we obtain a **monotone map** $\rho : \mathcal{P} \rightarrow \mathcal{I}$.

Spectral semantics

Protocols, categorically

In the context of round-based, full-information, oblivious protocols. . .

The **protocol complex** is functorially related to the input complex $\mathcal{I}$:

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and the **protocol map** is natural in $\mathcal{I}$:

$$\begin{array}{ccc} \mathcal{I} & \xrightarrow{\pi_{\mathcal{I}}} & \mathcal{D}(\mathcal{P}(\mathcal{I})) \\ \phi \downarrow & & \downarrow \mathcal{D}(\mathcal{P}\phi) \\ \mathcal{I}' & \xrightarrow{\pi_{\mathcal{I}'}} & \mathcal{D}(\mathcal{P}(\mathcal{I}')). \end{array}$$

Protocols, categorically

In the context of round-based, full-information, oblivious protocols. . .

The **protocol complex** is functorially related to the input complex $\mathcal{I}$:

$$\begin{array}{ccc} \mathcal{I} & & \mathcal{P}(\mathcal{I}) \\ \phi \downarrow & \text{sComp} \xrightarrow{\mathcal{P}(-)} \text{sComp} & \downarrow \mathcal{P}\phi \\ \mathcal{I}' & & \mathcal{P}(\mathcal{I}'), \end{array}$$

and the **protocol map** is natural in $\mathcal{I}$:

$$\begin{array}{ccc} \mathcal{D}(\mathcal{I}) & \xrightarrow{\pi_{\mathcal{I}}^{\vee}} & \mathcal{D}(\mathcal{P}(\mathcal{I})) \\ \phi_* \downarrow & & \downarrow \mathcal{D}(\mathcal{P}\phi) \\ \mathcal{D}(\mathcal{I})' & \xrightarrow{\pi_{\mathcal{I}'}^{\vee}} & \mathcal{D}(\mathcal{P}(\mathcal{I}')). \end{array}$$

A directed limit

In particular, **iterating** a protocol $(\mathcal{P}, \pi)$ yields a sequence

$$\mathcal{D}(\mathcal{I}) \xrightarrow{\pi_{\mathcal{I}}^{\vee}} \mathcal{D}(\mathcal{P}(\mathcal{I})) \xrightarrow{\pi_{\mathcal{P}(\mathcal{I})}^{\vee}} \dots \xrightarrow{\pi_{\mathcal{P}^2(\mathcal{I})}^{\vee}} \mathcal{D}(\mathcal{P}^n(\mathcal{I})) \xrightarrow{\pi_{\mathcal{P}^n(\mathcal{I})}^{\vee}} \dots ,$$

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Dualising, we obtain a sequence

$$\mathcal{I} \xleftarrow{\rho_0} \mathcal{P}(\mathcal{I}) \xleftarrow{\rho_1} \mathcal{P}^2(\mathcal{I}) \xleftarrow{\rho_2} \dots \xleftarrow{\rho_{n-1}} \mathcal{P}^n(\mathcal{I}) \xleftarrow{\rho_n} \dots$$

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The limit of this diagram is a **spectral space** denoted by $\mathcal{P}^{\infty}(\mathcal{I})$.

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The limit of this diagram is a **spectral space** denoted by $\mathcal{P}^{\infty}(\mathcal{I})$.

This construction defines a **functor**

$$\begin{aligned} \mathcal{P}^{\infty} : \text{sComp} &\longrightarrow \text{Spec} \\ \mathcal{I} &\longmapsto \mathcal{P}^{\infty}(\mathcal{I}). \end{aligned}$$

Characterising task-solvability

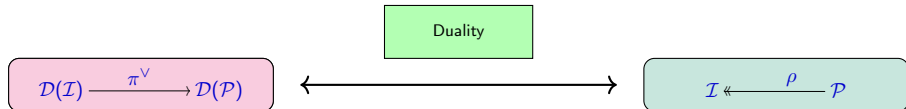
Our contribution : spectral semantics

$$\mathcal{I} \xrightarrow{\pi} \mathcal{D}(\mathcal{P})$$

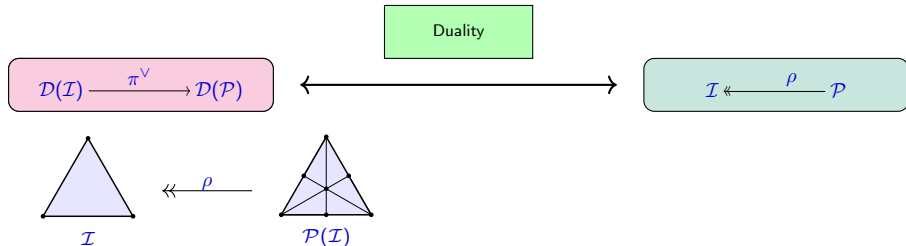
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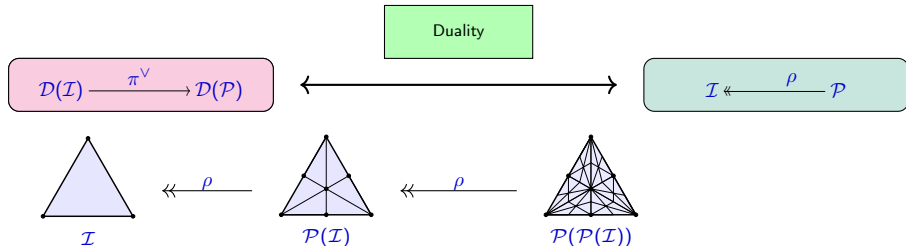
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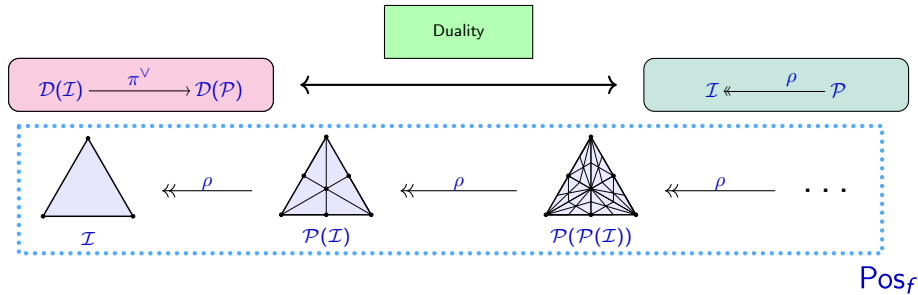
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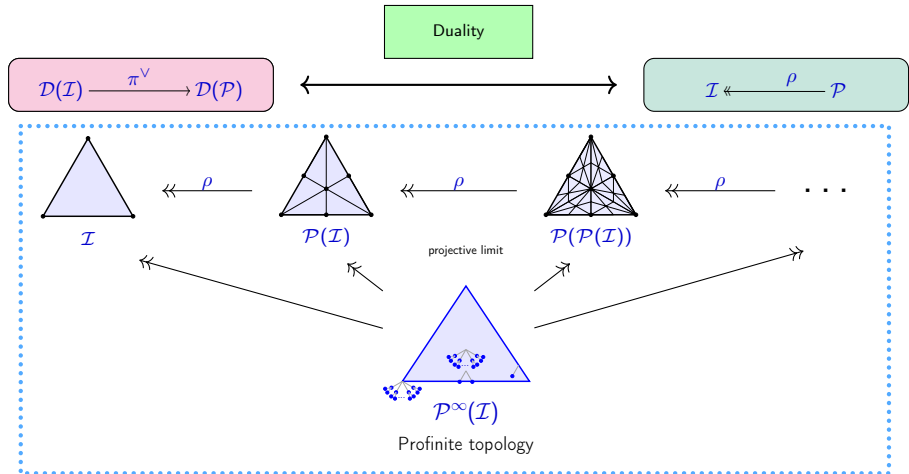
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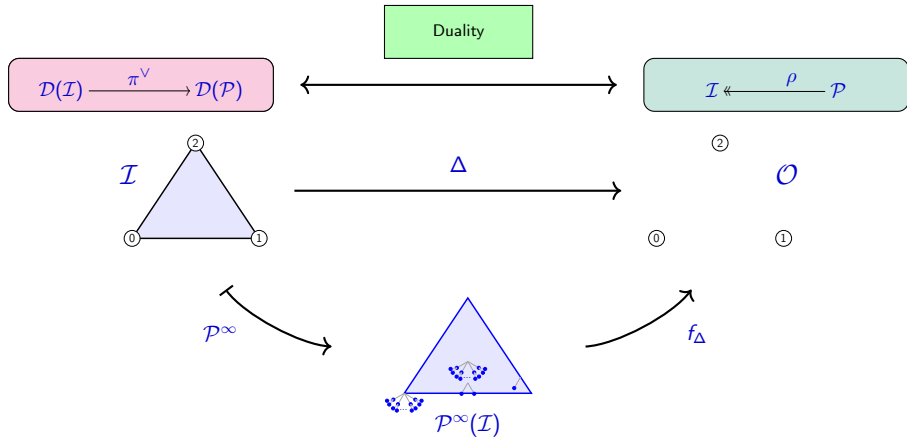


Our contribution : spectral semantics



Spec

Our contribution : spectral semantics



Theorem (C., Godard)

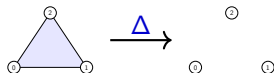
A colorless task $(\mathcal{I}, \mathcal{O}, \Delta)$ is solved by a protocol $(\mathcal{P}, \pi)$



There exists a spectral map $f_\Delta : \mathcal{P}^\infty(\mathcal{I}) \rightarrow \mathcal{O}$.

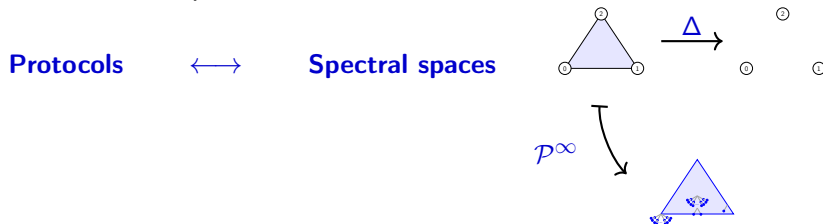
Conclusion

We provide a topological characterisation of task-solvability for a large class of iterated protocols.



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The use of Stone duality and categorical methods allows us to encode

- distributed knowledge using T_0 topology,
- epistemic dynamics as a projective limit,

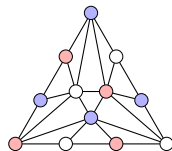
while generalising the original approach.

Distributed computability theorems

Models/tasks with identifiers

Study of labelled spectral spaces

Correspondence anonymous $\leftrightarrow$ identifiers.



Distributed computability theorems

Models/tasks with identifiers

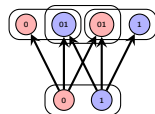
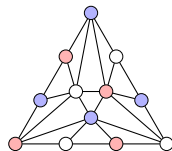
Study of labelled spectral spaces

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Asynchronous and probabilistic models

Event structures as protocols.

Spectral space associated to an event structure.



Distributed computability theorems

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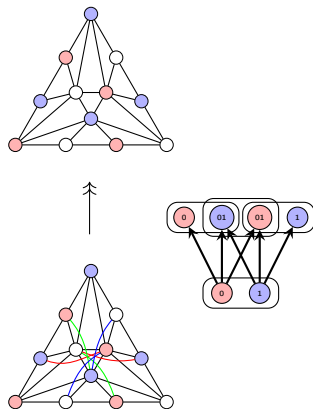
Spectral space associated to an event structure.

Equivalence of models

By topological methods

Bisimulation by retract.

Sub-spaces and sub-models.



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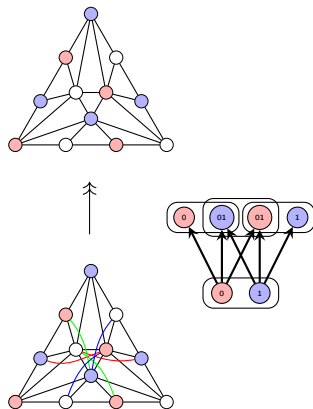
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Open maps and (co)algebras.

Epistemic-temporal logic via duality.



$$(D_U(\phi \Rightarrow \psi) \Rightarrow D_U\phi \Rightarrow D_U\psi)$$

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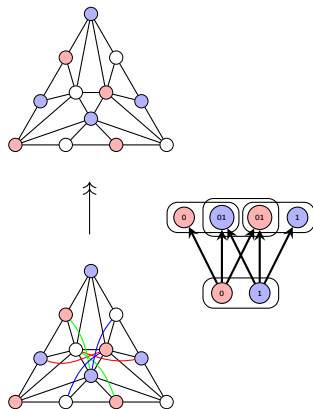
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Formalisation in a proof assistant



Thank you!

The spectral space of a protocol

We can describe the space $\mathcal{P}^\infty(\mathcal{I})$ concretely.

Points x_σ are **protocol sequences**, sequences (σ) of simplices with

$$\begin{aligned}\sigma_n &\in \mathcal{P}^n(\mathcal{I}) \text{ and,} \\ \rho_n(\sigma_{n+1}) &= \sigma_n,\end{aligned}$$

The **open topology** is generated by the sets

$$U_{n,\sigma} := \{(\tau) \in \mathcal{P}^\infty(\mathcal{I}) \mid \tau_n \geq \sigma\},$$

for $\sigma \in \mathcal{P}^n(\mathcal{I})$ i.e. the generating open sets in each $\mathcal{P}^n(\mathcal{I})$.

The **specialization order** $\leq$ on $\mathcal{P}^\infty(\mathcal{I})$ is defined by

$$x_\sigma \leq x_\tau \iff \forall n \in \mathbb{N} \quad \sigma_n \geq \tau_n \text{ in } \mathcal{P}^n(\mathcal{I}),$$

the opposite order of the point-wise order on protocol sequences.

The spectral space of Iterated Immediate Snapshot

Recall that the IIS protocol corresponds to the **barycentric subdivision** functor $\mathcal{B} : \mathbf{sComp} \rightarrow \mathbf{sComp}$.

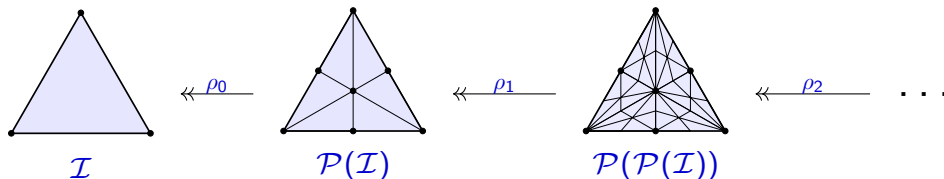
Protocol sequences consist of “**smaller and smaller**” simplices.

Thus, for every sequence (σ) , $\exists! x \in |\mathcal{I}|$ such that $\{x\} = \bigcap |\sigma|$.

However, many sequences result in the same point in $|\mathcal{I}|$

For every $x \in |\mathcal{I}|$, there exists a unique **maximal** point (σ^x) such that $x \in \bigcap |\sigma^x|$.

This means that $|\mathcal{I}|$ is homeomorphic to the subspace of $\mathcal{B}^\infty(\mathcal{I})$ consisting of **maximal points**.



Revisiting the original result

We saw that for **barycentric subdivision**, the maximal points of $\mathcal{B}^\infty(\mathcal{I})$ contains $|\mathcal{I}|$ as its subspace of maximal points.

This falls into the context of **Wallman spaces**.

Given a compact **normal space** i.e. $|\mathcal{I}|$,
and the choice of a **normal** basis for its topology, i.e. $(|\sigma_n|)_{(\sigma) \in \mathcal{B}^\infty(\mathcal{I})}$,
we obtain a spectral space i.e. $\mathcal{B}^\infty(\mathcal{I})$ whose **maximal points** are
isomorphic to the normal space we started with.

A **mesh-shrinking** subdivision protocol defines a normal basis for $|\mathcal{I}|$.

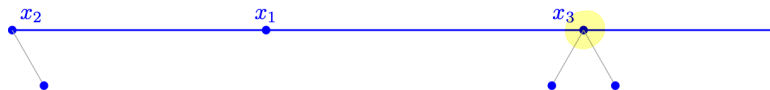
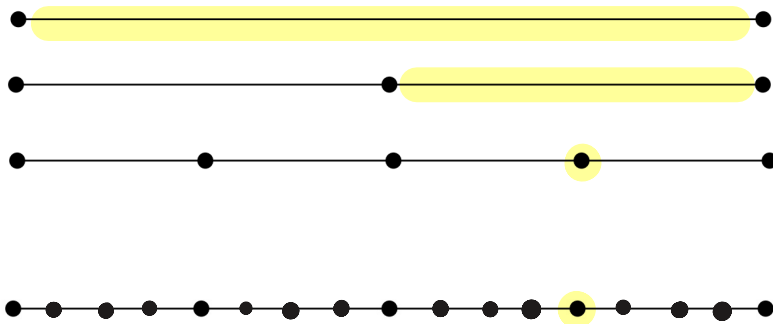
Thus, we recover the original theorem via the following lemma:

Lemma

For a mesh-shrinking protocol $(\mathcal{P}, \pi)$, and a task $(\mathcal{I}, \mathcal{O}, \Delta)$, there exists a continuous map $|\mathcal{I}| \rightarrow |\mathcal{O}|$ respecting Δ if, and only if, there exists a spectral map $\mathcal{P}^\infty(\mathcal{I}) \rightarrow \mathcal{O}$ respecting Δ .

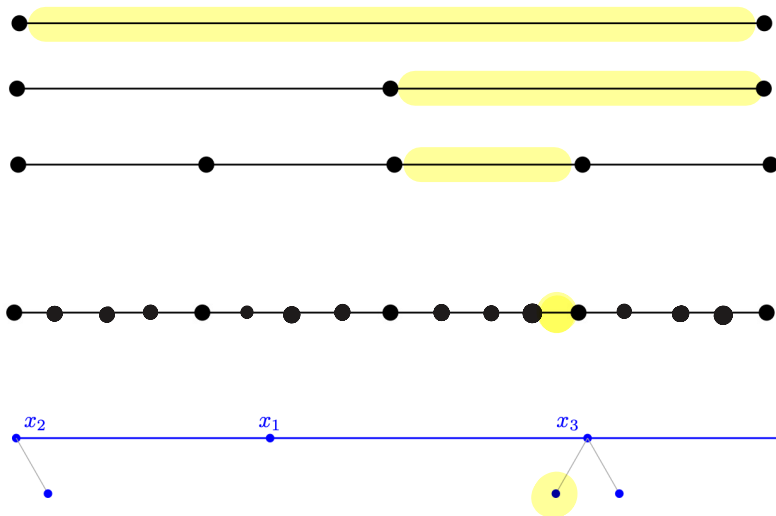
This is essentially **simplicial approximation** via spectral spaces.

The spectral space of Iterated Immediate Snapshot

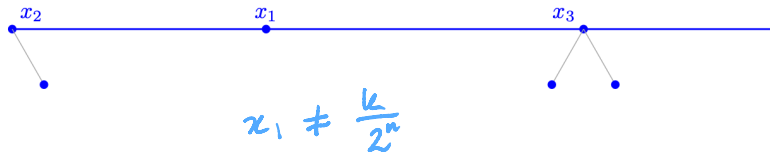
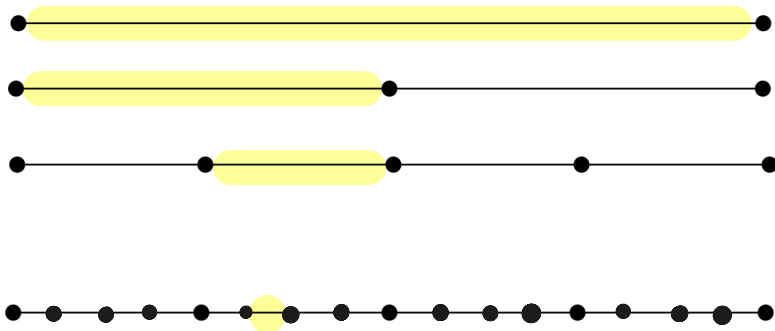


$$x_3 = \frac{k}{2^n}$$

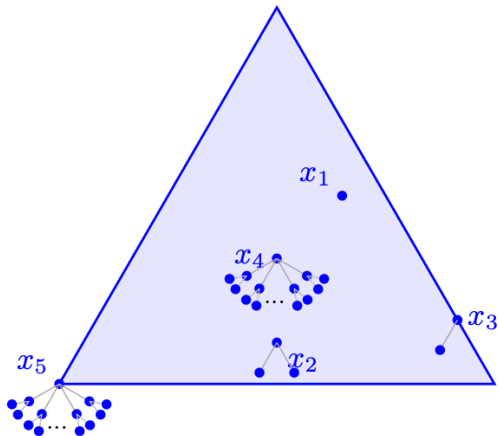
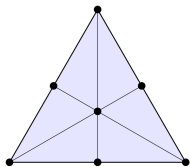
The spectral space of Iterated Immediate Snapshot



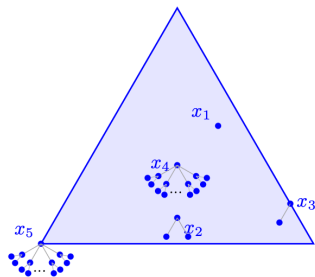
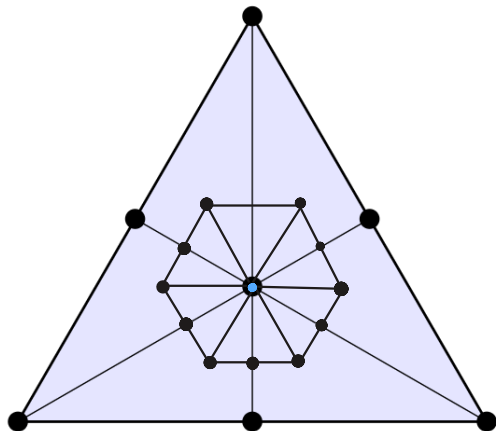
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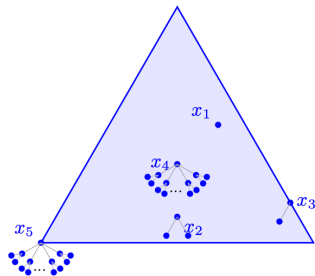
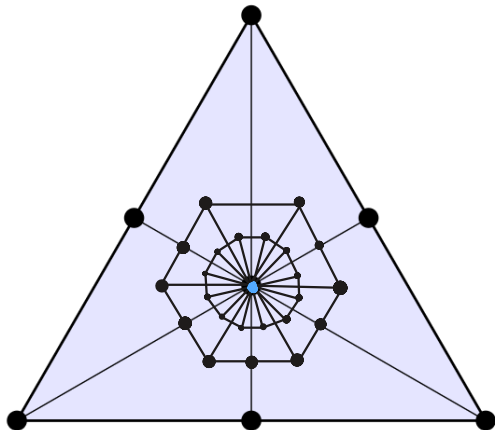
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